

About UNAVCO

UNAVCO is a non-profit university-governed consortium funded by the National Science Foundation (NSF) and The National Aeronautics and Space Administration (NASA).

- 106 member universities in the USA
- 94 associate members worldwide

UNAVCO provides data and expertise relating to an array of geophysical methods including GPS, Terrestrial Laser Scanning (TLS), lidar for airborne laser swath mapping, borehole seismometers, strainmeters, and tiltmeters, and interferometric synthetic aperture radar (InSAR).

Researchers from institutions around the world use UNAVCO instruments, data, and expertise to study the earth and how it is changing.

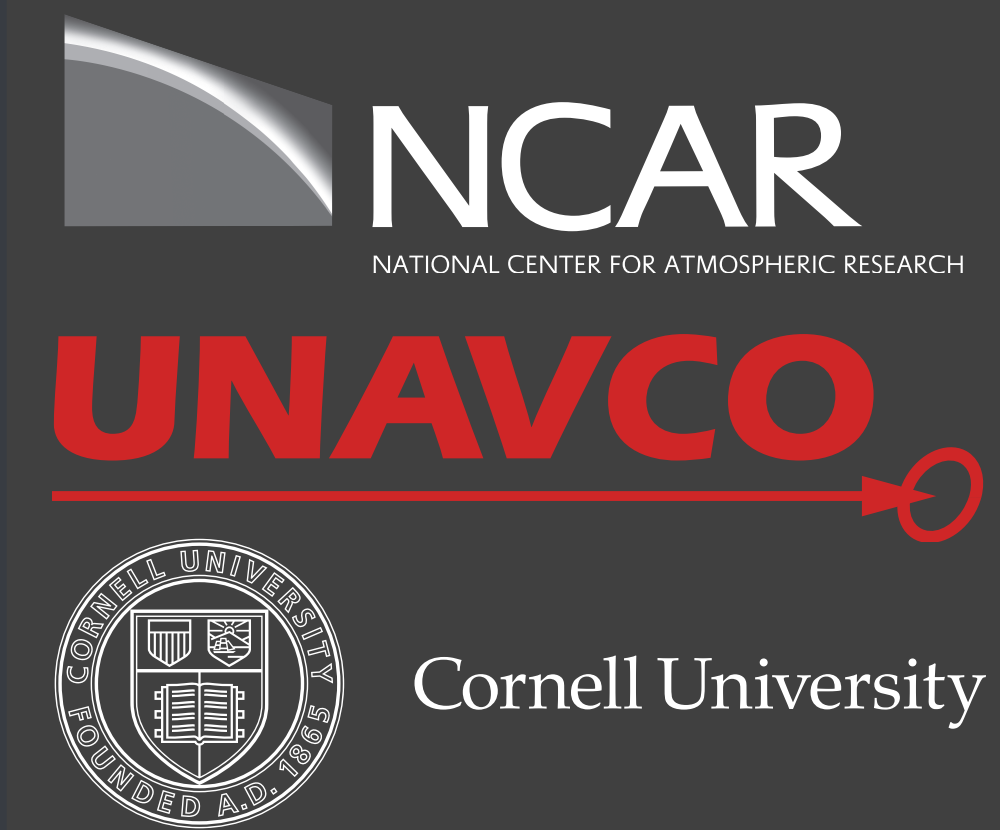
UNAVCO provides services that support research informed by geodesy (the study of Earth's shape, gravity field, and rotation)



Research community produces work supported by UNAVCO

About EarthCollab

Enabling Scientific Collaboration and Discovery through Semantic Connections, or EarthCollab, is part of the EarthCube Program at the National Science Foundation. EarthCollab includes two use cases: a VIVO implementation at UNAVCO and another at NCAR's Earth Observing Laboratory (EOL), Cornell, where VIVO was originally developed, is also part of the collaborative project.



Data Structures

VIVO has been primarily implemented by research universities, especially in the life sciences. This is reflected in the VIVO-ISF ontology. To capture concepts relevant to UNAVCO, we must extend the ontology. We will use concepts from established ontologies whenever possible.

- VIVO-ISF: people, organizations, publications. VIVO-ISF is already a compilation of ontology terms, including concepts from the OBO foundry (Open Biological and Biomedical Ontologies), CITO (Citation Typing Ontology), and BIBO (Bibliographic Ontology).
- DCAT: datasets and catalogs. DCAT (the Data Catalog Ontology) was designed to facilitate interoperability between data catalogs published on the web. DCAT contains concepts not captured in VIVO's treatment of datasets as a type of publication, such as landing pages and distribution information.
- GCIS: scientific instruments, platforms, and projects. GCIS (Global Change Information System) includes concepts such as sensors, scientific models, and platforms.
- EC: local EarthCollab ontology. UNAVCO operates hundreds of continuously operating GPS stations. Station is a concept not defined in any of the above ontologies and will be defined in EarthCollab's local ontology.

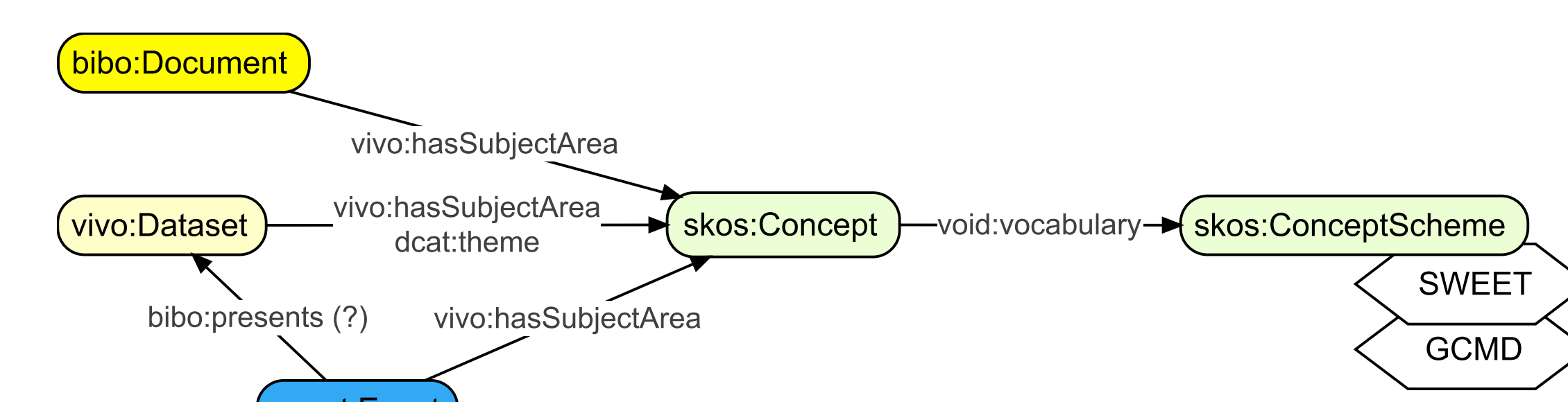
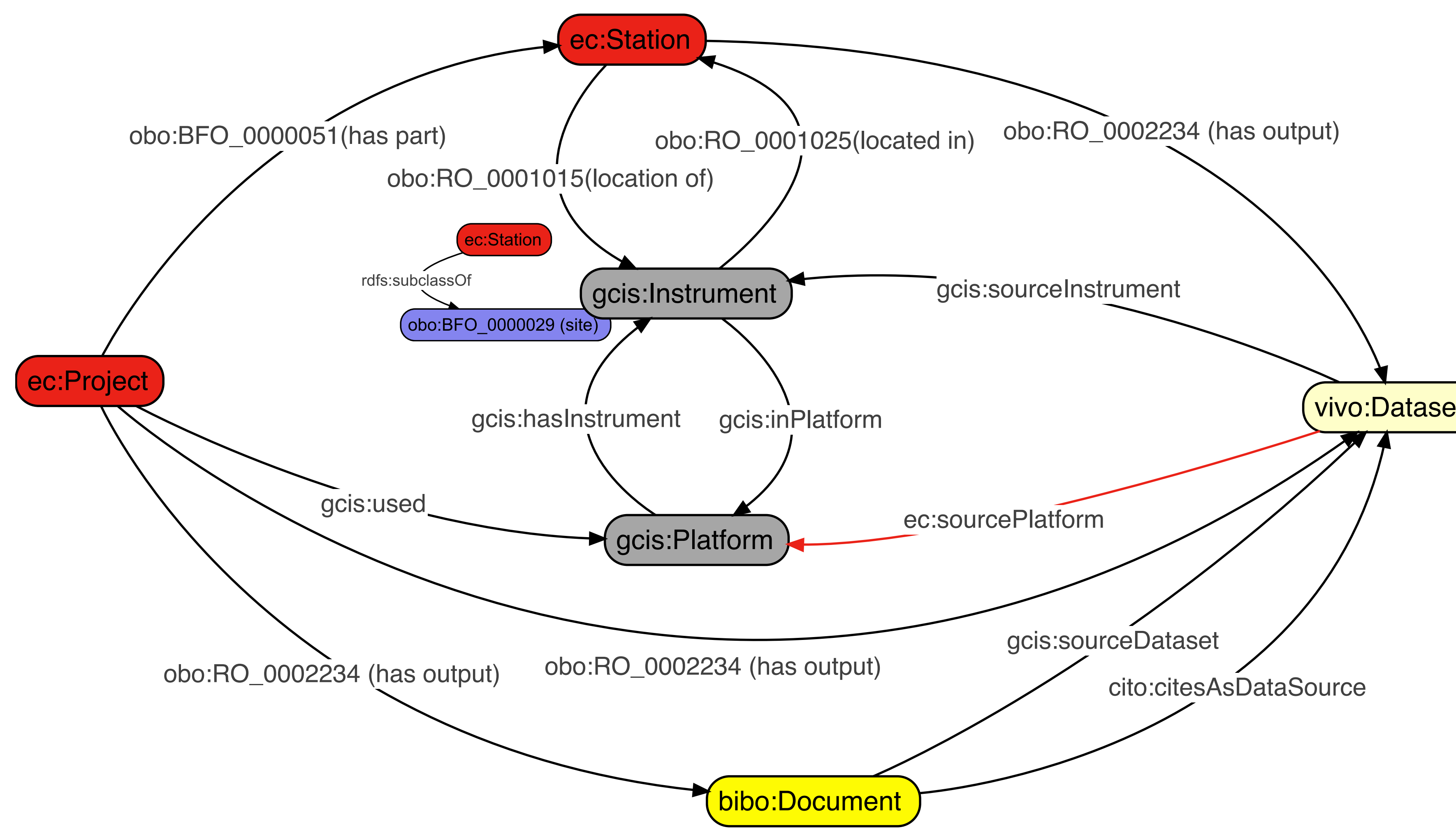
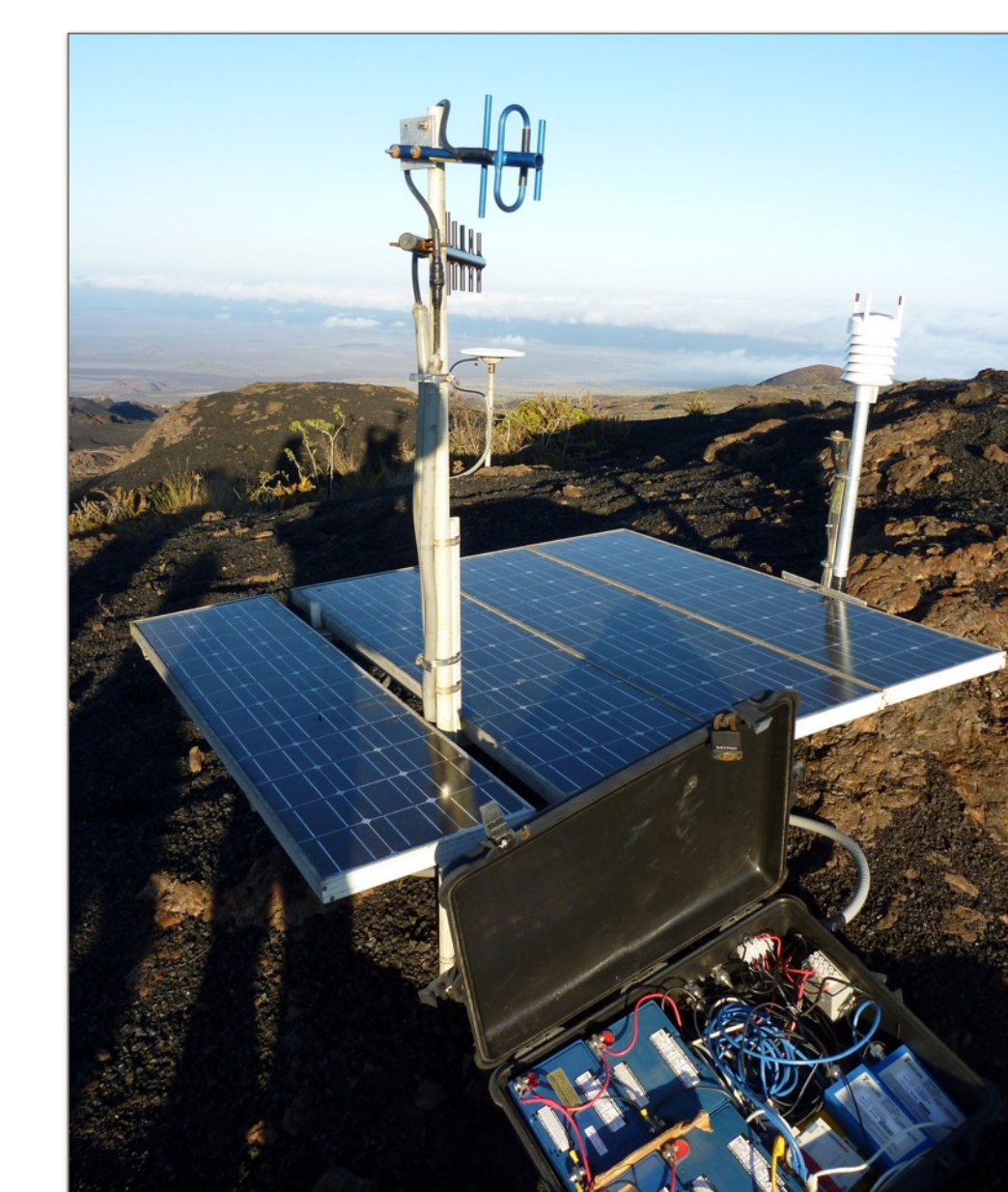


Figure 11 (left): Visual representation of a relationship not fully supported in the VIVO-ISF ontology. A project will have many stations which may host multiple instruments (e.g. GPS and co-located meteorological equipment), which are attached to one or more platforms. See Figure 14.

Figure 12 (above): Datasets can be linked to a major geophysical event, such as an earthquake. The products shown, and others such as software and models, will be tied to skos:Concepts, which will be pulled from controlled vocabularies whenever possible.



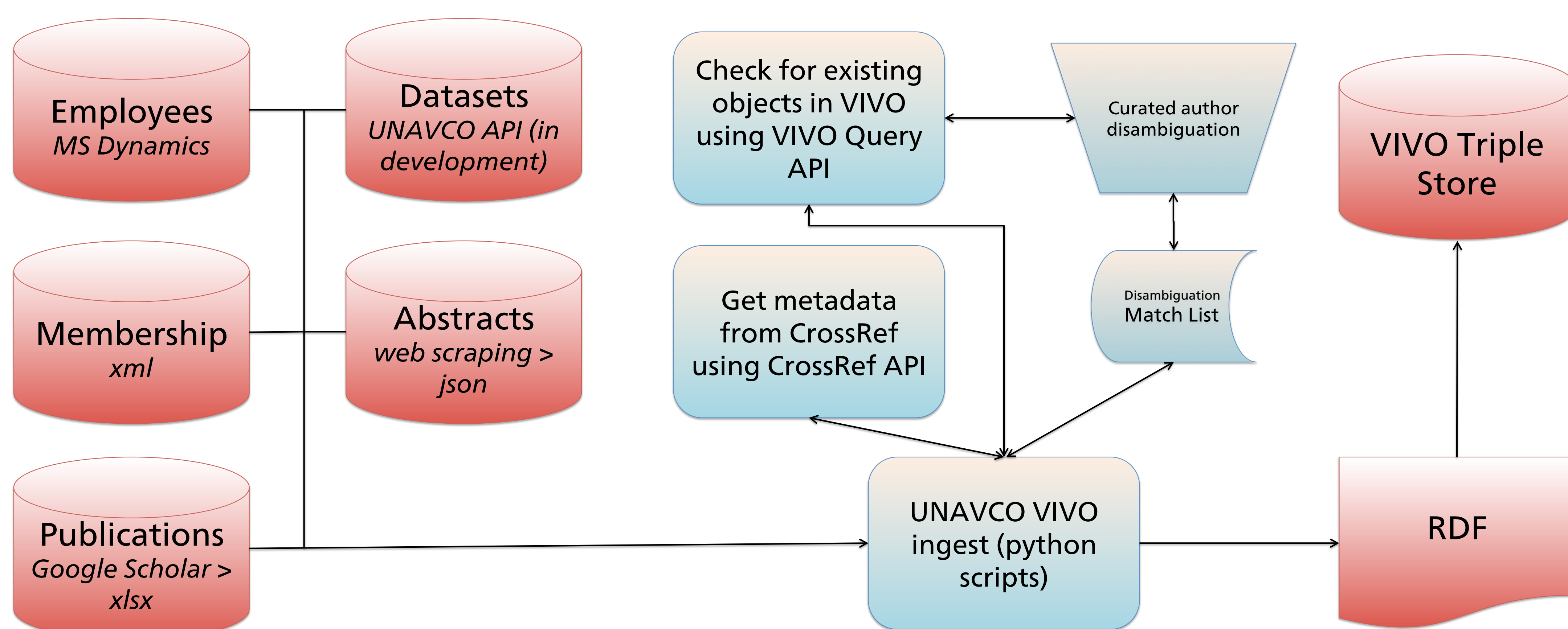
Dataset DOIs

Figure 13 (below): We have implemented a Digital Object Identifier (DOI) assignment mechanism, currently for GPS/GNSS data and select inSAR data, and will be expanding their use to other data types. DOIs provide persistent unique identifiers and can ease cross-linking efforts.

| GPS Data Set Citation Summary | |
|-------------------------------|--|
| Identifier: | 10.25751/1212 |
| Title: | Plate GPS Network |
| Abstract: | USGS Continuously Operating GPS Network |
| Address: | 1485 Foothill Parkway, P.O. Box 108, Boulder, CO 80502 |
| Author: | UNAVCO, Inc. |
| Publication: | UNAVCO, Inc. |
| Description: | Permanent Station |
| Series Name: | Active |
| Date Range: | 2011-10-01 through 2014-03-31 |
| Creation: | Original Work (DOI: 10.25751/1212) Plate GPS Network, USGS Continuously Operating GPS Network, UNAVCO GPS Data Set |
| Revised Publication: | 2012 |
| Data Availability: | Accession record |
| Data Format: | UNAVCO Data Product (DOI: 10.25751/1212) UNAVCO Data Product (DOI: 10.25751/1212) UNAVCO Data Product (DOI: 10.25751/1212) |
| See Also: | UNAVCO Data Product (DOI: 10.25751/1212) UNAVCO Data Product (DOI: 10.25751/1212) UNAVCO Data Product (DOI: 10.25751/1212) |

Figure 14 (left): A completed GPS site on the caldera rim of the Sierra Negra volcano, Galapagos Islands. The station includes an array of equipment types, including the GPS antenna and receiver, solar power source, radio transmitter, and meteorological equipment.

UNAVCO Data Ingest Process



Data Ingest Details

UNAVCO's current data ingest process is illustrated by the flowchart on the left (Figure 15). A major challenge has been collecting data for VIVO from a number of separate databases maintained by separate people.

Ingest process highlights:

- Python code uses rdflib library to allow output of multiple RDF file types.
- Using the VIVO Query API, checks VIVO database for duplicate objects. Unique identifiers, such as DOIs, are used when possible and string matching used otherwise. This module is also used to check for collisions when generating random URIs.
- Includes a rough implementation of a disambiguation process using fuzzy string matching and manual curation. Name variations that are confirmed are stored in a 'Match List' file, which is checked by the script before requesting curator input.
- Currently, triples are loaded into VIVO using the Add/Remove RDF tool. As development continues and we begin to automate ingest, triples will be loaded using the VIVO Update API.

Figure 16 (right): Example of ingest script requesting curator input to match an author's name to names already in the VIVO database.

```

num  first  middle  last  uri          type  score
0    Ryan S.      Cross  per274395  vcard  87
1    Paul        Cross  per980517  vcard  70
2    P           Cross  per118559  vcard  -
3    P.          Cross  per678453  vcard  -
4    PA         Cross  per621912  vcard  -
  
```

Author Ryan Cross may already exist in the database. Please choose a number

Progress

Figure 17 (right): UNAVCO has made significant progress identifying data sources and ingesting the data into VIVO. Additionally, we have begun requesting employees and select community members sign up for ORCID, a service that provides a unique identifier, publications search capabilities, and a public API.

Future Work

- Begin cross-linking VIVO instances across institutions.
- Enhance geospatial capabilities of VIVO by extending ontology and application.
- Automate ingest process, including ingest from ORCID.
- Add GPS station data and link to datasets already in VIVO.
- Conduct task-centered usability testing to determine how the VIVO application can be further tailored to a geoscience-centered use case.
- Explore integration with other EarthCube web projects.

Initial Data Ingest Progress

| Category | Count |
|---------------|-------|
| People | 527 |
| Publications | 4062 |
| Datasets | 3230 |
| Abstracts | 437 |
| Organizations | 236 |